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# Optimum Design of Liquified Natural Gas Bi-lobe Tanks using Finite Element, Genetic Algorithm and Neural Network

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Abstract. A comprehensive set of ten artificial neural networks is developed to suggest optimal dimensions of type 'C' Bi-lobe tanks used in the shipping of liquefied natural gas. Multi-objective optimization technique considering the maximum capacity and minimum cost of vessels are implemented for determining optimum vessel dimensions. Generated populations from a genetic algorithm are used by Finite Element Analysis to develop new models and find primary membrane and local stresses to be compared with their permissible ranges using PYTHON coding. The optimum design space is mathematically modeled by training ten artificial neural networks with design variables generated by the Taguchi method. The predicted results are compared with actual design data and the 93% achieved accuracy shows the precision of the developed design system.

Keywords: Liquefied Natural Gas, Bi-lobe tank, Finite Element Method, Genetic algorithm, Artificial Neural Network, Taguchi method.

# 1. Introduction

Without any doubt and by increasing energy demand, Natural gas (NG) is pronounced a perfect option for bridging the gap between the current energy market with pollutant fuels and the next decade's new energies [1]. Natural gas is also recognized as an environmentally friendly [2, 3], economical [4, 5], safe [6, 7] and clean [8, 9] fuel with lower emissions (NOX, SOX, …) in comparison with heavy fuel oil (HFO) and other relevant fuels. The remarkable issue about NG is the increasing demand for Liquified Natural Gas (LNG) in the global market, which makes it one of the fastest-growing and issues in the energy industry [1]. Recently, due to many superiorities from environmental and economic aspects, LNG and its related issues has attracted the attention of many scientists regarding LNG market and trading [10, 11]; transport section including railroad [12, 13], road [14, 15] and heavy-duty vehicle [16]; marine transportation [17, 18], infrastructure and its impact [19-21]; gas station [22]; LNG Tankers [23-25] and cargo containment system [26-28]; and LNG tank design [29, 30]. Because of significant reduction of volume, transportation of NG in liquefied states, i.e., Liquefied Natural Gas (LNG) and Liquefied Petroleum Gas (LPG) [31] by specific ships (Liquefied Gas Tankers or Gas Carriers) increases the economic advantages of using these fuels [32]. Thus, from the transportation point of view and due to the special properties of LNG, the affordable and economical way to transport LNG is using cargo ships. Meanwhile, regarding the widespread consumption of LNG as an appropriate alternative fuel [33] and dramatic increase of energy demand in one hand, and its sufficient accessible resources considering current production rate, on the other hand, gas fuel will last over 50 years more than oil (52.5 years). Hence, considering the impressive changes made in LNG equipment and construction technologies and based on the International Energy Agency estimation, there is sufficient supply for 250 years of consumption [33-35], and by considering the impressive changes made in LNG equipment and construction technologies, the necessity for



scrutinizing LNG fuel tanks and carriers looks more and more inevitable [18-21]. Generally, various types of tanks with different capacities are used for transporting LNG including prismatic, spherical, membrane, semi-membrane and independent tanks [36]. On the other hand, there are 3 independent types of tanks including Type 'A, B, and C'; while type 'C' also is divided into 3 subtypes: Cylindrical, Bi-lobe and Tri-lobe. According to  $IMO<sup>1</sup>$ , type 'C' tanks are more safe and reliable, with easier fabrication and installation process [37, 38]. Independent type 'C' tanks are flexible and competitive, and the demand for small and medium LNG carriers have been increased for coastal operation, nowadays [30]. The flexibility of this type of vessel during Boiling of Gas (BOG) and its pressure management zone accompanied by the fact that no secondary barrier is required for them, increase the interest of industrial authorities for utilizing them. Hence, Wang et al. [39] studied the strength evaluation of independent Type 'C' LNG carriers using finite element method (FEM). They analyzed bi-lobe tanks and their major components including tank shell, longitudinal central bulkhead, stiffener rings, and saddle supports, considering  $ASME<sup>2</sup>$  Boiler and Pressure Vessel (BPV) [40] requirements and IGC<sup>3</sup> codes [41]. Buckling of bi-lobe tanks under external pressure was studied and a complete procedure for evaluating the structural strength of a tank and its other accessories was derived. The analysis of spherical type LNG tanks under diverse static loads was also addressed by Shin and Ko [23]. Stress analysis of saddle support for horizontal pressure vessels was addressed by Kumar et al. [42] using ANSYS software and applying the mathematical method based on ASME BPV codes [40]. Yao et al. [43] determined the thickness of various parts of type 'C' LNG tank by implementing ANSYS FEM software under various loads. Shin et al. [44] used ASME Sec VIII Div. 2, IMO and IGC codes [41] to design a type 'C' LNG fuel storage tank with capacity of 500 m<sup>3</sup>. Senjanović et al. [45] requested for a remedy for misalignment of bi-lobe tank heads in LPG carriers. The results of their research indicated that the reason for this unwanted phenomenon is the high-stress concentration that occurs in Y-joint.

Bi-lobe tanks have also two great privileges compared with cylindrical tanks including; lower construction cost than that of 2 individual cylindrical tanks with the same volume, and lower occupied space than 2 individual vessels, considering the need for respecting minimum standard space between two cylinders. Hence, because of increasing interest in the application of bi-lobe tanks, this paper scrutinized the optimum design of type 'C' LNG Bi-lobe tanks, used for carrying and transporting LNG by ships and marine transport sector. Accordingly, no comprehensive study has been found in the literature that addresses the optimum design of LNG Bi-lobe tank design. Considering an available space for installing an LNG tank, there is no code or approved procedure for designing optimum vessel dimensions. Here, a comprehensive design methodology was presented for determining the optimum dimension of bi-lobe tanks for various available spaces. In other words, considering width, length, and height of available space in a ship, determining optimum dimensions of a bi-lobe with maximum capacity and minimum cost has not been addressed before. Hence, by considering codes and standards, design conditions, construction method and determining other technical parameters such as mechanical properties of proposed material (AISI 304L) at the specific working temperature; optimal design of Bi-lobe tanks has been studied by simultaneous employing FEM and Genetic Algorithm (GA) optimization method. The aim of this multiobjective optimization problem was to concurrently increase tank capacity and reduce its construction cost. Subsequently, it was shown that how the results of 144 designed cases were used to train a set of accurate Artificial Neural Networks (ANN) and develop an applicable tool for designing an optimum bi-lobe for any specific space.

#### 2. Methodology

A type 'C' Bi-lobe tank can be imagined as two horizontal cylindrical tanks joined together as shown in Fig. 1). This vessel can be defined by its major dimensions: shell length (l'), body radius (r), and deviation of each tank from the symmetry plane (a). Therefore, the total length (l) and width (w) of the vessel can be calculated as follows:

$$
l = l' + 2r \tag{1}
$$

$$
w=2(r+a)
$$

Initially, the dimensional constraints of Bi-lobe tanks were selected as variables based on desired tank volume and their dimensional ratios. To meet relevant tank installation location and ship dimensions mandatory IGF<sup>4</sup> codes [46], and to guaranty independency of tank design from rules, regulations and restrictions; these constraints, as ships' installation space, were presumed as hypothetical rectangular cubes (HRC) whose sides (L, H, and W) act as upper limits for designed tanks outer dimensions (l, h, and w). In other words, it is required to determine optimum dimensions of a Bi-lobe, i.e. l, h, and  $w$ , that can be inscribed in a rectangular cube with length L, height H and width W (Fig. 1).

After determining the levels of an experiment for volume and dimensional ratios of HRC and saddle angles, 72 cases for constraints were created by the factorial method. Afterward, the multi-objective optimization function was proposed to maximize tank capacity and minimize construction cost, simultaneously. Hence, considering 2 different states of cost-tovolume importance factors (IF), 144 cases were analyzed and optimized by integration of FEM and GE. Eventually, the optimum outputs, including best dimensions and objective functions, were separately used for training 10 ANNs, whose

 $\overline{a}$ 



<sup>1</sup> International Maritime Organization (IMO)

<sup>2</sup> the American Society of Mechanical Engineers (ASME)

<sup>3</sup> International Gas Carrier (IGC)

<sup>&</sup>lt;sup>4</sup> International Code for Ships Fuelled by Gases or Other Low-Flashpoint Fuels (IGF)

best architectural structure was selected by Taguchi Design of Experiments (DOE) algorithm, to comprehensively forecast the feasible region of optimal design. The schematics of this trend is illustrated in Fig. 2.





Fig. 2. Methodology schematics

Before any attempt for generating a method for determining bi-lobe tanks optimum design and parameters, design parameters, constraints, and objectives are needed to be specified.

At the design temperature of -163° C, the design vapor pressure of type 'A' tanks -considered as atmospheric tanks- is less than 0.7bar, while it is about 4.5 bar for independent type 'C' Bi-lobe tanks. At this temperature, the total carrying capacity for ships with 3 and 4 Bi-lobe tanks is about 25000m3 and 35000m3 respectively [47]. Thus, to cover all considerable volumes and acceptable dimensions, the desired volume range of HRC, in which tanks are inscribed, is considered between 500 to 9000m3. This continuous range of volume should be covered appropriately in this study. Therefore, to reach a finite number of problems, 4 amounts out of this range were considered in this research. Besides, to cover various dimension ratios, every volume was considered for 9 different dimensional ratios (Table 1). These ratios were selected deliberately to omit large and small ratios of L/W and W/H that lead to thin shells with low volume or thick shells with high cost.







Hence, 36 various sets of dimensions were specified (Table 2) and each was utilized in 4 different optimization problems considering 2 different saddle angles based on relevant codes [48], i.e. 120° or 150° [48] and 2 diverse cost-to-volume IF ratios, i.e  $\alpha/\beta = 0/1$  and 0.2/0.8. Obviously, when using 0 for cost the main objective was to just consider maximum volume during optimization. On the other hand, during considering 0.2 for cost and consequently 0.8 for volume, the effect of the cost was a little increased during optimization. The reason for delimiting IF between these two amounts is that; further increasing cost IF did not lead to any better design parameters since the effect of maximum volume during optimization was more important than the effect of cost for a ship. On the other hand, values of volume IF out of this specified range led to a point where tank's volume was very small and unreasonable. Consequently, the optimization problem were solved for 144 cases via a super-computer by implementing GA optimization in the ABAQUS environment using PYTHON scripting. In this study, whole calculations were thoroughly based on three-dimensional FEM analysis performed according to standard design specifications of  $LG<sup>1</sup>$  carrier ships and IGC code [41] requirements.



The Type of material has a great role in the design of LNG Bi-lobe tanks. 36% Ni-Fe steel, 9% Ni steel, stainless steel type AISI 304L, and Aluminum alloy type 5083 are generally used for fabricating LNG tanks at cryogenic temperature of - 163°C [49]. Since austenitic stainless steel sheets SA240 -Tp 304L is the most common material used for Bi-lobe tanks, it was selected as design material in this research. The chemical and mechanical properties of 304L are presented in Error! Not a valid bookmark self-reference. and Error! Reference source not found. respectively:

Table 3. Typical chemical compositions of 304L used in LNG tanks [49]





#### 3. Finite Element Simulation

The main objective of using finite element technique in this research was to find the stresses at critical points during pressure loads and compare them with their permissible amounts. Accordingly, there are three important issues that must be considered in this step:

- 1- Specify the design points of Bi-lobe tanks and find the stresses in various design points.
- 2- Determine the category of stresses in design points.

3- Specify the permissible values for each stress categories an compare them with the stresses in design points.

Accordingly, tanks with various dimensions were needed to be simulated using FE software. These simulations were then used during optimization for determining optimum Bi-lobe parameters. Hence, a Bi-lobe tank with spherical heads, a longitudinal bulkhead, and shell reinforcing internal rings, was modeled and meshed in ABAQUS software. The element used here was S4R, i.e. a quadrilateral, stress/displacement shell element with reduced integration, whose converged size was determined during analysis. However, since optimization step was performed for various vessel sizes and it seems that for each stage of optimization convergence test should be performed, mesh size was converged by considering mesh-totank radius ratio, instead of its size. After trying various ratios of element size to tank radius, and considering the resulted von Mises stress, this ratio was finally chosen to be 1:25. During FE analysis, tanks deadweight, weight of carrying liquid and internal pressure generated from vapor pressure and specified by USCG1 [51] and IMO [45], were the loads considered during analysis. Saddles apply reaction forces to the tank, and they have freedom of slight movement along tank axis to diminish the effect of any longitudinal thermal expansion. Thus, to simulate the effect of saddles, mechanical boundary conditions were considered to limit movements of saddle-shell contact area along transverse and vertical directions, i.e., Y and X axes respectively.

As explained in the above list, the design points, stress in design points and their categories must be calculated and specified. The design points are shown in Fig. 3. These points consist of:

a) Junctions of two surfaces where the stresses are primary local, i.e., head to head (D), shell to head (E), shell to reinforcement ring (F), and shell to shell (G).

b) Points far from junctions on the head (A), shell (B), or bulkhead (C), where the stresses are primary membrane.

The maximum amount of primary membrane stresses must not exceed permissible strength of the shell and head material at design temperature and the maximum amount of primary local stresses must be less 1.5 times permissible strength of shell material [48].



Fig. 3. Spots for reading stress on the vessel

#### 4. Optimization

The next step for optimum design generation was a combination of GA and FEM to optimize the cases defined within the defined dimensional constraints, using Python coding. The optimization code was included in a PDE file, generated during modeling Bi-lobe tanks, for determining optimum tank dimensions shown in Fig. 4. This trend, depicted in Fig. 5., was repeated for each generated set of constraints in the previous step. The design parameters should clearly show Bi-lobe design dimensions, hence, tank radius (r), deviation from the symmetry plane (a), shell length (l'), saddle angle (Y), head thicknesses  $(t_1)$ , shell thickness  $(t_2)$ , stiffener rings thickness  $(t_3)$ , and longitudinal bulkhead thickness  $(t_4)$  are the required design parameters; while, total width  $(w)$ , length  $(l)$ , and height of the tank  $(h)$ , are considered to be 3 of 4 inputs to the problem. To have a good image from the proposed Bi-lobe type 'C' tank, a vessel with its dimensional parameters is shown in Fig. 4.

Thereafter, the multi-objective function should be defined considering minimum construction cost and maximum capacity (volume). After a primary investigation from market and pressure vessel manufacturers, two parameters were found to be more effective on the cost of the vessel, i.e. weight and manufacturing cost. Though the price of various metals does not remain constant and many political, economic, etc. issues affect their prices, in this research the cost of SS304L at the time



of this study was considered to be 2.9 \$/Kg. Considering about 30% extra cost for manufacturing per weight of the vessel, the cost function is 1.3 times vessel weight multiplied by 2.9 \$/Kg. The cost function must be minimized while the tank volume must be maximized and these two objective functions must be considered simultaneously. On the other hand, these two functions do not have the same order and their effect on the combined objective function needed to be balanced. After getting the price of various Bi-lobe tanks from the manufacturers, it was found that  $280\frac{\text{m}}{2}$  could be a suitable factor for volume function in this research. Obviously, this factor depends on material price, manufacturing costs, etc. and varies from time to time. Hence, the final objective function is defined as follows:

$$
Objective function (f) = -\alpha C + \beta V
$$
  
= -\alpha (vessel weight \* construction coefficient \* 2.9) + \beta (tank volume \* 280) (2)

C and V stand for cost and volume of a tank respectively, and  $(\alpha, \beta)$  are the weights or Importance Factors (IF) of cost and volume respectively, which were the 4th input to this optimization problem. These factors were considered to be (0,1) or (0.2,0.8) in this research. By using (0, 1) factors, only volume was intended to be maximized. However, considering maximum volume without including the cost of fabricating a vessel during optimization is nonsense and only maximum volume regardless of its price are investigated. On the other hand, increasing the weight of cost would lead to a tank with less volume while volume is more important than the cost and the payback time of CNG tanks is not much. Therefore, it was found that the maximum IF of 0.2 for Cost and 0.8 for volume fulfills this research's requirements.



Fig. 4. Bi-lobe tank dimensional parameters

To guarantee the creation of Bi-lobe tanks with proper geometry and enough strength under loading, two sets of constraintsshould be satisfied during various stages of the analysis. To avoid unnecessary analyses of tanks with improper Bi-lobes dimensions, the constraints shown by Eq. (3-a). were checked immediately after the creation of a new population (Bi-lobe tank dimensions) by GA. Besides, the maximum stress in different locations of Bi-lobes was checked as specified



by constraints in Eq. (3-b). during FE analysis. The maximum limits for stress constraints were designed according to ASME Sec II, part D subpart 1 [40] at specific design temperature for two local and primary stress categories. In this research, the minimum acceptable amount of maximum stress was also considered during optimization to avoid unreasonable thicknesses especially when 0 was taken as the weight for cost in the objective function. In other words, when there is no lower limit for maximum stress, all thick dimensions for thicknesses satisfy the upper constraints which consequently increase the weight and cost of fabricating a tank. Therefore, when a lower limit is considered for maximum stresses during optimization, thick shells were rejected during analysis.

Since both primary local stresses at the two cylindrical shells or head-shell junctures, and primary membrane stresses were generated on shells or heads far from the junctures or any discontinuity (Fig. 3), it was necessary to consider the permissible strength for each separately. As explained before, this important strength limit was considered in the constraints specified in Eq. (3-b).



In the next step of analysis, a parametrically modeled Bi-lobe tank in ABAQUS finite element software was recalled and during each optimization step, the generated parameters (population) by GA were used as new parameters for the model. It should also be noted that some other necessary design constraints were considered in PYTHON coding. For example, it was considered that head thickness (t<sub>1</sub>) cannot be lower than shell thickness (t<sub>2</sub>), thus, t<sub>1</sub> is greater or equal to  $t<sub>2</sub>$ .



Fig. 5. Simulation and optimization trend









Fig. 7. Predicted vs simulated optimum outputs (normal values)

Hence, considering the depicted approach in Fig. 5, the optimization process was performed for each output individually, and the convergence trend for optimization of the objective function (f) is shown as an example in Fig. 6. Finally, during optimization, the most suitable vessel dimensions were determined for each of 144 designed experiments, and the results were shown in Table A.1 (see the Appendix A).

## 5. Developing Artificial Neural Networks

Since, the optimization process just presents a set of discrete optimum points, which are not capable to cover all feasible region, the ANNs were implemented to predict the whole continues region of Bi-lobe tanks design parameters. The ultimate step for developing an optimum Bi-lobe tanks design system was to train and develop ANNs for predicting design parameters for any unexperienced problem. Hence, feedforward backpropagation ANNs were used to predict unexperienced optimal states by training them with optimal modes obtained from the previous steps. The developed ANNs were used to forecast all points in the optimal feasible region, whose meticulous performance was ensured by allocating one separate network with best architectural structure to each output (design parameter). In order to attain the best possible structure for neural networks, Taguchi Design of Experiments (DoE) algorithm was used and 18 sets of ANN features for proper coverage of design hyperspace were generated (Table 5).







Every created ANN was trained and tested 3 times with optimum outputs, and after evaluating the average amount of each accuracy estimator parameter (MPE<sup>1</sup>, MSE<sup>2</sup>, R-squared<sup>3</sup>), eventually, the structures with a maximum mean of accuracy were chosen as the best possible structures to predict each output parameter individually. There are various algorithms for training a neural network i.e. gradient descent, Newton method, conjugate gradient, quasi-Newton, and Levenberg-Marquardt. In this research, the Levenberg-Marquardt Algorithm (LMA), which is the fastest method and known as the Damped Least-Squares (DLS), was employed for training, although it usually requires a lot more memory. Hence, the process of randomly reserving 35% of each data for test and training ANN with the remaining ones, was repeated for each structure till achieving accuracy criteria of R<sup>2</sup>>0.95. The favorite ANN structures and their R-squared amounts after training were shown in Table 6 and the accuracy of trained ANNs could be observed by means of their QQplot depicted in Fig. . The developed optimum designer has the ability to predict optimum Bi-lobe tank dimensions for all inexperienced states. The schematics of this process is shown in Fig. 8.





#### Fig. 8. Mathematical modeling trend

To validate the accuracy of the developed optimum designer system, it was necessary to compare the results with available designs. Consequently, an unexperienced set of design parameters within their permissible ranges was defined and analyzed using GA-FEA, and its optimum design parameters were compared with those predicted by the developed ANNs, as shown in Table 7. The maximum amount of 6.4% error shown in Table 7 depicts the acceptable accuracy of the developed design system.

<sup>&</sup>lt;sup>3</sup> Coefficient of Determination  $(R^2)$ 



 <sup>1</sup> Mean Percentage Error (MPE)

Mean Squared Error (MSE)



#### 6. Results and Discussion

In this investigation, more than half a million tanks were generated by GA and about 120000 ones, which had passed dimensional constraints, were analyzed by FEM. Input design parameters and GA results are presented in Appendix A Table A.1.

The results of this study were divided to 3 parts: FEA, GA, and ANNs. Since junctures D, E, F and G in Fig. 3Error! Reference source not found. experience primary local stresses, they were known as critical areas with stress concentration. GA results presented in Appendix A Table A.1 show that by switching volume IF from 0.8 to 1, the required thicknesses increase significantly, because of neglecting cost effect. Besides, in more than 80% of cases, the optimum value of deviation (a) was between 0.35r and 0.80r. Hereafter and before discussing ANN results, it should be noted that all variables have been normalized between 0 to 1 for ANNs to gain a more rational engineering result. Besides, from construction and manufacturing viewpoint and considering commercial sheet thicknesses, the thicknesses and lengths were rounded up with scale of 1mm and 1cm respectively.

Fig. 9 illustrates the effect of each parameter on the objective function, while other parameters were set to the middle of their domains. This figure compares the effect of volume and volume-to-cost IF on the objective function, with up to 35% and 29% influence respectively.

Figure 10 shows the effect of selected inputs within their normalized range on output while 4 other inputs were kept constant at their midrange.



Fig. 9. Parameters effect percentage on objective function

Using 5 specified inputs and ten trained networks predicts one output, the optimal predicted design spaces were 11 unimaginative 6-dimensional hyperspaces. On the other hand, 3D curves could only be implemented to show the effects of a maximum of 3 parameters on output while keeping the rest of variables constant. In Fig. 11, 3D trend of outputs in response to two inputs was shown. By varying the amounts of constant parameters, sets of quadric surfaces completely change. Thus, these charts may be used to point the general behavior of output variables and not just for simple individual analysis. Regarding the number of inputs and outputs, 100 other sets can be plotted to show various responses.

Figure 11.a shows the increasing effect of volume and volume-to-cost IF on the objective function. Figure 11.b shows tank capacity has the main effect on thickness and Fig. 11.c depicts that L/W and W/H do not have a considerable effect on tank thickness.





(c)

Fig. 11. Output response to multiple inputs



#### 7. Conclusions

A comprehensive study has been conducted for the optimum generation of Bi-lobe tanks for LNG fuel transportation. The developed optimum designer receives dimensions of available space for installing a Bi-lobe tank and suggests designs with maximum volume and best fabricating cost. The most applicable dimensions were considered and the optimum design of tanks was generated using GA and FEA using Python coding in ABAQUS software. The results were then utilized to train 10 ANNs to predict the optimum Bi-lobe dimensions for a new design. Accordingly, the most important results can be summarized as follows:

- The FEA results show that stress concentration occurs in the junctures of shell-shell, horn of saddles, shell-head or head-head. The self-limiting characteristics of stresses at junctures form secondary [48] stresses and beside primary membrane stresses, generate primary local stresses and are allowed to increase up to 1.5 times tank material permissible strength. However, even with this increased amount of permissible strength, it is recommended to use a stiffener ring for saddles.
- GA results show that the best value for the tank deviation parameter (*a*) is between 0.35r and 0.80r.
- Since stress concentration at the horn of saddle with 120 contact angle is more than other angles, the volume of Bilobe tanks with 0.8 IF is much less than the rest. The results also show that lower thicknesses, less volume and reduced amount of cost were obtained by applying cost IF.
- The resultant optimum design parameters of Table 8 lead to the following conclusions:
	- 1. Increasing saddle angle leads to decrease in stress concentration and therefore a reduction in minimum required shell thickness.
	- 2. Increasing the cost IF leads to cheaper tank but smaller in capacity.
	- 3. Escalation of volume leads to more shell thickness and cost, while augmentation of saddle angle reduces the thickness
	- 4. Optimum saddle angle for smaller tanks is around the midrange (120 to 150), meanwhile, larger tanks require larger saddle angles.
	- 5. Tanks with higher volume, require more shell thickness. Meanwhile, for the relatively wider tank, the thicker plate is required.

# Author Contributions

M. Salarkia reviewed the literature and extracted all the standards, regulations and available design information regarding LNG transportation, performed all the simulations, optimization and finite element results and acquired the main results; S. Golabi supervised the whole research, planned all steps of the project, conducted the design strategy and reviewed and approved the final version of the manuscript, and; B. Amirsalari assisted to develop whole artificial Neural Networks.

# Conflict of Interest

The authors declared no potential conflicts of interest with respect to the research, authorship, and publication of this article.

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#### Nomenclature



- 
- $L$  Length of hypothetical rectangular cubes  $w$  Tank width
- 
- $R^2$  Coefficient of determination
- 
- 
- Rody radius Body radius W Width of hypothetical rectangular cubes

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#### Appendix A

Table A.1. Optimum states generated by GA















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