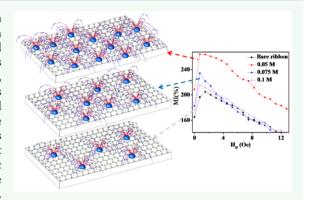
Article

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1 Controlling Magnetization of Gr/Ni Composite for Application in 2 High-Performance Magnetic Sensors

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ABSTRACT: Graphene (Gr), a well-known 2D material, has been under intensive investigation in the past decade due to its high potential applications in industry and advanced technological elements. Composites made of Gr and other functional materials especially magnetic materials have opened opportunities in sensors, health care monitoring, magnetic devices, etc. Here, we report a mass production of Gr/Ni composite powders using an electrochemical exfoliation/deposition method with different magnetic strengths of the final composite material. We applied the magnetic composite materials in a magnetoimpedance (MI)-based sensor and observed a significant enhancement in the MI effect and its field sensitivity. Such magnetic composites with controlled magnetization strengths are coated on the MI-ribbon sensor surface, and different MI responses are observed. Furthermore, the MI response of a ribbon coated with a Gr/Ni layer is



21 theoretically determined based on an electrodynamic model with a qualitative consistency to experimental results. Our 22 comprehensive study can be applied in high-performance functionalized MI-based magnetic sensors and devices. 23

KEYWORDS: surface modification, electrochemical exfoliation, magnetoimpedance sensor, graphene/nickle composite, 2.4

magnetic nanoparticles

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1. INTRODUCTION

26 In recent years, graphene (Gr), a two-dimensional (2D) 27 hexagonal lattice of sp² hybridized carbon atoms, has attracted 28 comprehensive research interest because of its fascinating 29 electrical, mechanical, chemical, and optical properties and its 30 potential application in next-generation electronics, 1,2 energy 31 storage devices, 3-5 and composite-based materials. 6-8 Integra-32 tion of Gr or the Gr family with various nanoparticles (NPs) 33 allows the development of new nanocomposite materials with 34 novel properties and highly promising applications in 35 bioscience, ^{9–11} microwave elements, ^{12,13} sensors, ¹⁴ etc. ¹⁵ The formation of hybrid structures made of Gr and 37 nanoparticles represents new functionality and properties which offer them for applications in technology and industry 39 due to their developed characteristics related to separate 40 counterparts. 16 Due to preserving the characteristics related to 41 the NPs, Gr-nanoparticle hybrid structures are promising for 42 their electronic, optical, structural, and magnetic properties 43 that are unavailable in bulk materials. In addition to the above-44 mentioned properties they show the potential for use in 45 bioapplications.¹⁷ Specially, Gr materials are alluring when 46 combined with magnetic NPs, for sensor and catalytic 47 properties, with enhanced sensitivity and selectivity. 16-19

A wide range of magnetic sensors, such as anisotropic 48 magnetoresistance, giant magnetoresistance, tunneling magne- 49 toresistance, the Hall effect, and magnetoimpedance (MI) 50 sensors are now available. Among them, sensors based on the 51 MI effect have been considered as an effect element with 52 higher field sensitivity and appropriate signal intensity for 53 magnetic sensing purposes. $^{20-22}$ The MI effect is defined as 54the change of the electrical impedance of a conducting 55 ferromagnetic (FM) with high transverse magnetic perme- 56 ability (μ_t) in the presence of a static magnetic field.^{23–29} By 57 applying an external magnetic field, the skin depth (δ) changes 58 due to the change in μ_t , thus varying the impedance of the FM 59 element. In the case of the ribbon, with width w and length L, 60 the impedance is approximately

$$Z = (1 - i)\frac{\rho L}{2w\delta} = \frac{(1 - i)L}{2w} (\pi \rho f \mu_t)^{1/2}$$
 (1) 62

where ρ is electric resistivity, f is frequency of the current, and i 63 = imaginary unit. Therefore, the impedance of the ribbon is a 64 function of frequency, driving current, and the external dc 65

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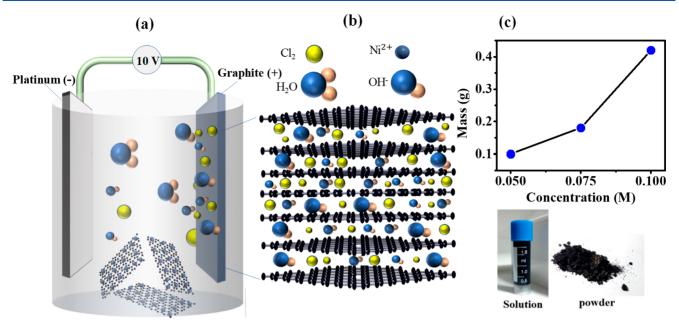


Figure 1. (a) Schematic of the proposed mechanism when magnetic Gr/Ni is produced. (b) The position of OH^- and Cl^- ions is illustrated between graphite sheets. These ions increase the interlayer distance of the graphite. Then, the Cl gas is produced and can exert an excessive force to separate graphite layers. Then, the distributed Gr sheets in the solution can trap Ni^{2+} ions. (c) Concentration of electrolyte solution and final mass of magnetic Gr/Ni composite.

66 magnetic field $(H_{\rm dc})$ through μ_t and δ . The environmental 67 sensing ability and improving the magnetic field sensor 68 performance are two aspects of this phenomenon. Enhance-69 ment of magnetic field sensitivity has been reported by coating 70 layers with different magnetization and conductivities on the 71 surface of MI sensors. $^{28,30-34}$ The physical origins are well-72 known through the magnetic proximity effect, 8 decrease of 73 surface roughness, and magnetic exchange interactions 74 between sensors and coated magnetic layers. Also, surface 75 modification of the ribbons has been reported intensively for 76 detection of environmental elements through magnetic and 77 nonmagnetic interactions with the environment. 21

Recently, we applied electrochemical exfoliation of Gr using a solution containing Ni ions which leads to simultaneous exfoliation of Gr and deposition of Ni between Gr sheets. Here, we extend this method toward fabrication of composites with controllable magnetic properties and introduce a useful technological application of such magnetic Gr/Ni composites. We investigate the application of such a composite in MI sensors with an observed enhanced ratio and sensitivity when coated atop an MI sensor.

In order to obtain a comprehensive study and achieve a 88 physical description behind the experimental results, we 89 proposed an electrodynamic model to explain the MI behavior 90 in the studied structure. Our model is based on solving the 91 linearized Maxwell equations for the electromagnetic fields 92 coupled with the Landau—Lifshitz—Gilbert (LLG) equation 93 for the magnetization dynamics of the sensor. These results can 94 be used in interpreting the experimental results of our designed 95 MI sensors. Both theoretical predictions and experimental 96 observations confirm the MI response changes due to coating 97 of magnetic composites with different magnetization strengths 98 qualitatively. The fundamental physical phenomenon de-99 scribed in this work can be used for the development of 100 magnetic field and environmental sensors based on the MI 101 effect.

2. EXPERIMENTAL SECTION

2.1. Preparation of Gr/Ni Composite by Electrochemical 102 Exfoliation. We used a two-electrode system for electrochemical 103 exfoliation of graphite. Platinized silicon (100 nm thickness and lateral 104 dimension of $0.5 \times 10 \text{ cm}^2$) was used as the cathode electrode. Also, a 105 graphite foil ($2 \times 10 \text{ cm}^2$) was used as the anode. The distance 106 between the two electrodes was kept constant at 2.8 cm. Electrolyte 107 solutions were prepared by dissolving NiCl₂·6H₂O powder in water 108 with three different molar ratios of 0.05, 0.075, and 0.1. A constant 109 voltage (+10 V) was applied to the electrodes to provide expansion, 110 exfoliation of graphite, and deposition of Ni. The voltage was 111 maintained constant for 20 min to complete the exfoliation/ 112 deposition process. Afterward, the product was collected using 113 vacuum filtration and repeatedly washed with deionized (DI) water. 114 The resulted product was dispersed in water for sonication.

The mechanism of electrochemical exfoliation is depicted in Figure 116 f1 la,b. For an explanation of the exfoliation/deposition mechanism, see 117 f1 previous reports. 15,35 Reported processes are confirmed by the effect 118 of initial NiCl₂/water concentration on exfoliation, as depicted in 119 Figure 1c. In this figure, adding NiCl₂ results in higher production of 120 Gr sheets, but below and above these values, final products do not 121 show magnetic properties. Because OH⁻ and Cl⁻ are responsible for 122 the production of Gr flakes, therefore the increasing molarity of NiCl₂ 123 results in more exfoliated production content. As we are mainly 124 interested in magnetic properties of our final products, we therefore 125 investigate all of our samples made with 0.05, 0.075, and 0.1 M. 126 Continuing, we represent a comprehensive study of products; 127 investigate their conductivity, magnetization, and MI measurements; 128 and discuss the mechanism of MI theoretically.

2.2. Characterization. The crystalline structure of samples was 130 characterized using an X-ray diffractometer (XRD) with Cu K α (λ = 131 0.154 nm) radiation. Fourier transform infrared (FTIR) spectra were 132 recorded via a Bruker (Tensor 27) FTIR spectrometer with resolution 133 of 1 cm⁻¹ in transmission mode at room temperature. X-ray 134 photoelectron spectroscopy (XPS) was done in an ESCA/AES 135 system equipped with a concentric hemispherical analyzer (CHA, 136 Specs model EA10 plus). The size and morphology of elements were 137 observed by tunneling electron microscopy (TEM-Philips model 138 CM120). Room temperature magnetization measurements were done 139 via a vibrating sample magnetometer (Meghnatis Daghigh Kavir Co.). 140

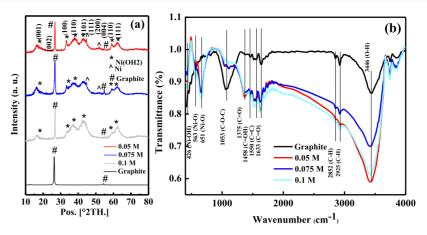


Figure 2. (a) X-ray diffraction (XRD) and (b) FTIR spectra of 0.1, 0.075, and 0.05 M samples and graphite foil.

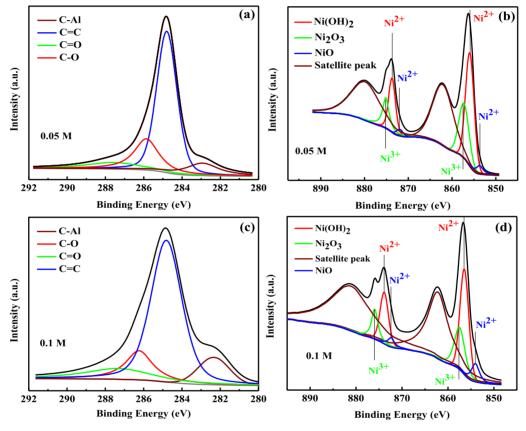


Figure 3. High-resolution XPS spectra of C 1s and Ni 2p core level of Gr/Ni sample of (a, b) 0.05 M and (c, d) 0.1 M.

141 Current—voltage (I-V) measurements were done by a two-probe 142 method using a Keithley (model 2450) sourcemeter. Field emission 143 scanning electron microscopy (FESEM) for samples was done by a 144 VEGA TESCAN instrument.

2.3. Magnetoimpedance (MI) Measurement. The conventional melt-spinning technique is used for the preparation of amorphous Co-based ribbons, $Co_{68.15}Fe_{4.35}Si_{12.5}B_{15}$ (1 mm width, 40 mm length, and ~20 μ m thickness). The Gr/Ni composite with different molarities of 0.05, 0.075, and 0.1 M of NiCl₂ was droptocated on the two surface sides of the ribbon at room temperature. Evaporation of water and nanoparticle solution was required before the data acquisition process started. An external magnetic field was produced by a solenoid and applied along the ribbon axis to measure the MI response of the samples by the four-point probe method. Different frequencies of ac current were supplied to the longitudinal direction of the ribbon by a function generator (GPS-2125), with a 50

 Ω resistor in the circuit. The impedance was measured using the voltage and current across the sample using a digital oscilloscope (GPS-1102B). The MI ratio is defined as

MI% =
$$\frac{Z(H_e) - Z(H_{e_{\text{max}}})}{Z(H_{e_{\text{max}}})} \times 100$$
 (2) 160

where Z refers to the impedance as a function of the external field H_e . $_{161}$ The $H_{e_{\rm max}}$ is the maximum field applied to the samples during the MI measurement. The longitudinal direction of samples was perpendicular to the Earth's magnetic field to minimize its effect on the MI response of samples.

Table 1. Fitted XPS Data for fwhm and Peak Positions for C 1s and Ni 2p Core Level of 0.05 and 0.1 M Gr/Ni Sample

	C 1s (C—Al)		C 1s (C=C)		C 1s (C—O/C—Cl)		C 1s (C=O)	
sample	B.E. (eV)	fwhm (eV)						
0.05 M	282.5	2	284.8	1.3	285.9	1.7	287.6	4.1
0.1 M	282.6	2.6	284.8	1.6	285.7	1.7	287.3	4.1
	Ni 2p _{3/2} (Ni ²⁺)		Ni 2p _{3/2} (Ni ³⁺)		Ni 2p _{1/2} (Ni ²⁺)		Ni 2p _{1/2} (Ni ³⁺)	
sample	B.E. (eV)	fwhm (eV)						
0.05 M	855.9-853.7	2.3-1.9	857.4	2.7	873.6-871.9	1.8-1.9	875.1	1.7
0.1 M	856.4-854	2.3-2	857.4	2.7	873.9-872.4	2.2-1.8	875.9	1.6

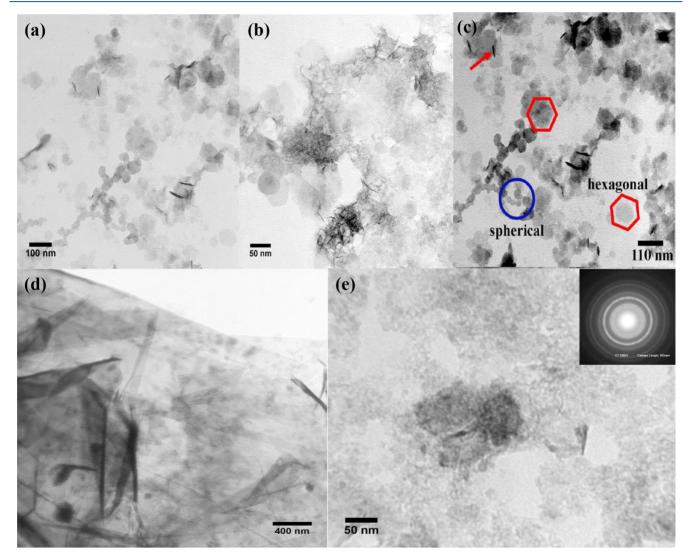


Figure 4. TEM images of (a) 0.1 M, (b) 0.075 M, and (c) 0.05 M samples and (d) the micron boundary size of Gr sheets. (e) SAED pattern of the 0.05 M sample.

3. RESULTS AND DISCUSSION

166 XRD analysis was employed to confirm the crystalline 167 structures of Gr/Ni composites as shown in Figure 2a. The 168 dominant diffraction peak of the initial graphite foil at 2θ = 169 26.31° indicates an interlayer d-spacing of 3.38 Å, while in the 170 final samples the (002) diffraction peak appeared at 26.16° 171 with an interlayer d-spacing of 3.40 Å. There are some 172 diffraction peaks that belong to Ni(OH)₂. One broad 173 diffraction peak at around 2θ = 13.45° and another one at 174 2θ = 33.2° represent the (001) and (100) planes of the β -175 phase, respectively (JCPDS 001-1047), while (110) and (111)

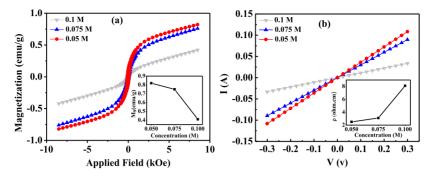


Figure 5. (a) VSM magnetization plots of 0.05, 0.075, and 0.1 M samples. The inset shows the saturation magnetization of samples versus concentration. (b) Current–voltage (I-V) curve measurement for 0.05, 0.075, and 0.1 M samples, and the inset shows the resistivity (ρ) of samples versus concentration.

sample.

187 found to be 43 and 32 nm, respectively. Also, TEM images, 188 explained later, proved the observed sized.

To elucidate the interaction of Ni nanoparticles (Ni NPs) 190 with the Gr sheets, FTIR spectra were recorded and analyzed. 191 FTIR is a useful technique to confirm that the NPs are 192 anchored on the Gr surface, as shown by several groups. 37,38 193 Figure 2b shows the FTIR spectra of the graphite foil and 194 produced samples. It shows a number of oxygen functionalities 195 due to the presence of residual elements in the Gr. 39 The 196 absorption peaks at \sim 1633, \sim 1550, and \sim 1375 cm⁻¹ should be 197 assigned to stretching vibrations (v) of C=O. The presence of O-H is confirmed by the strong and broad band at 3446 cm⁻¹. The intensity of this peak is stronger for the synthesized Gr/Ni structures than the initial graphite foil which shows the effect of the aqueous solution of the experiment on generation 202 of hydroxyl elements. The absorption peak at 1053 cm⁻¹ 203 should be attributed to stretching vibrations (v) of C—O— C⁴⁰ that disappear after exfoliation. The bands at 2925 and 205 2852 cm⁻¹ are assigned to the asymmetric and symmetric 206 vibrations of C—H, respectively. 41,42 Comparing the FTIR spectra of graphite foil with the final sample, the spectrum of 208 Gr/Ni structures clearly exhibits a considerable red-shift 209 (particularly to the major vibration of C=C and -OH 210 bonds), which may be because of the Ni NPs bonding to the 211 Gr layers. 43 The absorption bands at 651, 563, and 426 cm⁻¹ 212 are attributed to the NiO and n(Ni—OH) vibration. 43

High-resolution XPS spectra are used to probe the chemical compositions of the 0.05 and 0.1 M Gr/Ni composites (Figure 3a-d). Peak positions and fwhm values are presented in Table 1. The presence of $Ni(OH)_2$ and Ni-oxides is observed using Ni 2p peaks, while no Ni is observed. However, Ni peaks were observed in the XRD measurements which reconfirms the presence of Ni compounds. This contradiction is expected as the XPS is able to probe the surface of the materials only. Also, 221 rather than the oxides at the surface of the Ni, there are other compounds that prevent Ni signatures from showing up.

The area ratios allow calculating the relative proportions of 224 atoms in each binding for a given element. The concentration 225 ratio of Ni:C was estimated using the following relation for 226 0.05 and 0.1 M samples:

$$\frac{C_{\text{Ni}}}{C_{\text{C}}} = \frac{I_{\text{Ni}}}{S_{\text{Ni}}} \times \frac{S_{\text{C}}}{I_{\text{C}}} \tag{3}$$

228 where C, I, and S are the elemental concentrations, XPS peak 229 area, and corresponding sensitivity factors. The relative surface ratio of $\frac{C_{Ni}}{C_C}$ for the 0.1 M sample is 0.36 which increases to 0.51

for the 0.05 M sample. Also $\frac{C_{Ni}}{C_O}$ for the 0.1 M sample is 0.71 $_{231}$ which increases to 0.85 for the 0.05 M sample, and $\frac{C_C}{C_O}$ for the $_{232}$ 0.05 M sample is 1.66 and increases to 1.93 for the 0.1 M $_{233}$

TEM images of samples are shown in Figure 4. Hexagonal 235 f4 structures appear in Figure 4a-c that are presumed to be 236 related to Ni(OH)₂ nanocrystals, whose crystallization at the 237 β -hexagonal phase was identified from our XRD data. Thes Ni- 238 based nanocrystals are separated by dashed lines in Figure 4c. 239 They have also different alignments/geometry, e.g., rolled up 240 structures, which are shown by an arrow in Figure 4c that 241 appears with more probability in samples made with higher 242 molarities, i.e., 0.1 M sample. Results dictate a small thickness 243 of the crystal, because they look to have thin planar geometry. 244 In Figure 4b,d we see crumpled Gr and nanocrystals sticking to 245 it for the 0.75 M sample. The nanocrystals (Ni-oxides, Ni, 246 Ni(OH)₂) appear to be randomly distributed on Gr sheets, 247 and this character is supposed to be the reason of their 248 superparamagnetic-like response (presented later). TEM 249 results confirm the size of Ni-based nanocrystals obtained by 250 XRD data. The brightness of Gr sheets appearing in this image 251 confirms their small thickness. The image in Figure 4d shows 252 micron-sized formation of Gr sheets which is in agreement 253 with dynamic light scattering (DLS) results with a determined 254 particle size of 1.2 μ m. The selected area electron diffraction 255 (SAED) pattern in Figure 4e, measured for randomly selected 256 Gr sheets of the 0.05 M sample, represents the polycrystalline 257 nature of the Gr.

To investigate the effect of the molarity of NiCl₂ on the 259 magnetic properties of the Gr/Ni composite, the magnetic 260 hysteresis loops of the 0.05, 0.075, and 0.1 M samples were 261 recorded at room temperature. The VSM results shown in 262 Figure 5a represent the superparamagnetic-like response of the 263 fs samples. By decreasing the molarity of NiCl₂, the magnet- 264 ization of the composite increases (see the inset of Figure 5a). 265 XRD results showed the lower concentration of Ni in samples 266 synthesized by higher NiCl₂ molarities. The formation of Ni or 267 $Ni(OH)_2$ depends on the concentration of OH^- at the 268 cathode. This means that increasing the molarity of NiCl₂ 269 results in the increasing generation rate of OH⁻ and therefore 270 the production ratio of $Ni(OH)_2$ with respect to the Ni would 271 increase. Consequently, by controlling the molarity of the 272 solution, the concentration of FM Ni and thus the magnet- 273 ization will be controlled. The XPS results are compared with 274 magnetization which indicates that the concentration of Ni to 275 Ni(OH)₂ is more in the 0.05 M sample and caused a higher 276

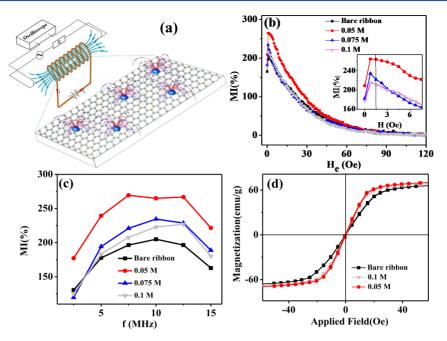


Figure 6. (a) Schematic illustration of the measurement setup for the MI response and the structural conditions in the MI sensor when the ribbon is coated with Gr/Ni composites. The influence of the Gr/Ni layer on the MI is related to stray fields induced by magnetic Ni NPs. The stray fields change the magnetization distribution in the magnetic ribbon and affect the permeability and the MI effect. (b) MI ratio as a function of applied magnetic field for the bare ribbon and ribbon drop-coated by Gr/Ni NPs with three different molar ratios. The inset shows an enlarged portion of the low-field MI curves. (c) Frequency dependence of the impedance response of all samples. (d) Magnetic hysteresis loops of the bare ribbon and ribbon drop-coated by Gr/Ni composite with molar ratios of 0.05 and 0.1.

277 magnetization. This also confirms that the conductivity of the 0.05 M sample is more than that of the 0.1 M sample which 279 has been seen by our I-V experiment. For I-V measurements, silver paste-coated pellets connecting wire were used. I-Vplots are linear, showing conductive behavior of all samples (Figure 5b). Resistivity of samples was determined by the linear fitting of *I*–*V* plots. Resistivity increases from the 0.05 M sample to the 0.1 M sample which is shown in the inset of Figure 5b. According to the aforementioned growth mecha-286 nism, we can interpret that as the molarity of NiCl₂ in solution increases, there is more OH⁻ generation on the cathode and more hydroxide elements in Gr that result in more resistivity in samples. XPS and XRD data show more hydroxide densities 290 and lower Ni elements for samples prepared from solutions with higher molarities of NiCl₂. 291

3.1. Magnetic Gr/Ni Detection by Magnetoimpedance Measurement: Testing of the Biosensor. In the biosensor sector, the detection of functionalized magnetic NPs 294 295 has become a current active research issue. 22,44 Besides high sensitivities, the NP detector should also have low power 2.96 consumption, small size, quick response, stability of operation 297 parameters, resistance against aggressive medium, and low cost. Different sensing techniques are employed for the NP detection: anisotropic magnetoresistance, 45 giant magnetoresistance, 46,47 and magnetoimpedance (MI) effects; in the 301 following, we try to improve the sensitivity of the later one 302 using our Gr/Ni composites. 303

To evaluate the potential applications in sensing devices, we sos study the MI magnetic field and frequency dependence for a co-based FM ribbon and later try to determine the effect of the stray fields introduced by the magnetic Gr/Ni NPs on the MI response. By applying an ac charge current with frequency f to the samples, we investigate how the impedance of the ribbon changes as a function of the external magnetic field. We

perform field sweep impedance measurements at the frequency 311 of f = 10 MHz (frequency where maximum MI was already 312 determined) for ribbon (as-cast) and ribbon drop-coated by 313 Gr/Ni NPs with three different molar ratios of 0.05, 0.075, and 314 0.1. The schematic illustration of the measurement setup for 315 the MI response and the structural features of the MI-based 316 sensor is presented in Figure 6a. As determined above, the 317 f6 lower the molarity of the samples, the higher the content of the 318 Ni in the sample. Each of the Ni NPs can produce a stray field 319 on the surface of the ribbon and thereby affect the magnetic 320 anisotropy and permeability of the ribbon. As can be seen from 321 Figure 6b, the MI ratio for the bare ribbon has the smallest 322 value and increases for the drop-coated samples. The 323 maximum values of the MI ratio are 201%, 218%, 238%, and 324 275% for the bare ribbon and the ribbon with the drop-coated 325 Gr/Ni composite with molar ratios of 0.1, 0.075, and 0.05, 326 respectively. The inset of Figure 6b shows an enlarged plot of 327 the low-field MI curves. One can see that the anisotropy field is 328 1.5 Oe for the bare ribbon, while for the drop-coated sample, 329 the amount of the anisotropy field decreases and reaches 1 Oe. 330 When the Ni NPs are affected by the external field, they can 331 produce a measurable stray field. As a result, the presence of 332 the Gr/Ni composite leads to a sizable increase in the MI ratio 333 near the anisotropy field and the displacement of the MI curve. 334 This finding is of practical importance, as the Gr/Ni composite 335 can be better used as a magnetic biomarker for applications in 336 medical diagnosis, especially in the cases in which Gr plays the 337 role of biomarking. So Also, compared to the reported 338 sensitivities in the literature 21,51 the sensitivity of our sample 339 may be much lower, but in using a biocompatible Gr-based 340 material, 10,14,17,18 our sample would show a valuable advantage. 341

In order to evaluate the difference between the MI ratio of 342 the bare ribbon and Gr/Ni composite-covered ribbon, we 343 measured the MI at different frequencies ranging from 1 to 15 344

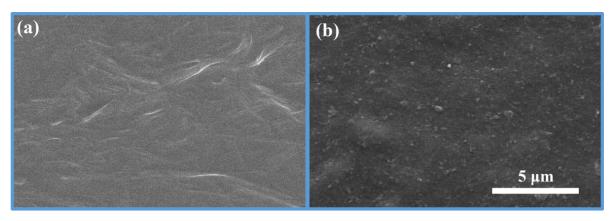


Figure 7. Field emission scanning electron microscopy (FESEM) images of (a) the bare ribbon and (b) ribbon drop-coated by Gr/Ni nanocomposite with molar ratios of 0.05.

345 MHz. The maximum MI ratio of all samples versus frequency 346 is plotted in Figure 6c. It is observed in Figure 6c that, for the 347 samples, by increasing the frequency, the maximum MI ratio 348 increases initially, reaches a maximum at f = 10 MHz, and then 349 decreases for higher frequencies. This trend is interpreted by 350 considering the relative contributions of moment rotation and domain wall (DW) motion, as both contribute to the transverse magnetic permeability and hence the MI response. 20,23,51 Note that when frequency increases well 354 above 100 kHz, the contribution of DW motion would be 355 damped because the presence of eddy current and moment 356 rotation becomes dominant.²⁰ Therefore, the MI ratio 357 decreases at high frequencies.

Finally, to investigate the effect of the drop-coated Gr/Ni 359 composite on the magnetic properties of the ribbons, the 360 conventional VSM method was used to obtain the magnetic 361 hysteresis loops. Figure 6d shows the magnetic hysteresis loops 362 of the bare ribbon and ribbon drop-coated by Gr/Ni 363 composite with molar ratios of 0.05 and 0.1. All the loops 364 are thin and narrow, and magnetization is saturated at a small 365 applied field, which shows their soft FM characteristics. 366 According to Figure 6d, after coating, the saturation field 367 decreases, and the differential magnetic permeability of the 368 sample which is proportional to the magnetization slope has 369 increased dictating a weak field-sensitive and magnetically 370 softer state. As mentioned before, the MI effect is a highly surface-sensitive phenomenon due to the low skin depth of the 372 ribbon. In this context, there are many reports on the surface modification of MI sensors by coating layers with different magnetization and conductivities. ^{31–33,52–54} All articles have 375 reported the increase in the MI ratio, and the physical origins are well-discussed through the decrease of surface roughness and the closed magnetic flux path^{31–33} and magnetic exchange 378 interactions between sensors and coated magnetic layers. 52,8 Also, some reports have used Gr-based materials and reported the better performances of their sensor device. 8,28,55-39 For example, the vertical Gr sheets may redistribute the surface 382 magnetic field, which is good for improving the transverse 383 permeability,⁵⁷ or the MnFe₂O₄-Gr oxide nanocomposite 384 increased the MI ratio due to the suppressed physical motion 385 of the MnFe₂O₄ NPs on the Gr sheet, as well as the enhanced 386 effective anisotropy of the sample.⁵⁶ Very recently, we coated 387 the (Gr nanoplates)/(yttrium iron garnet) (GNPs/YIG) 388 composite on a magnetic ribbon and showed that the 389 proximity-induced magnetism (PIM) in Gr adjacent to 390 magnetic YIG influences the magnetization of the GNPs to

make them a wholly magnetized plane.⁸ Such a magnetized 391 plane can be mounted on the surface of ribbon MI sensors, and 392 thereby the MI response is enhanced against the external 393 applied magnetic field significantly. However, in the case of 394 Gr/Ni composite, the difference in the magnetization of 395 composites is related to the difference in the amount of 396 magnetic particles in the composite and not only PIM. The 397 0.05 M sample has a higher impact on diminishing the 398 magnetic flux at the surface of the MI element due to higher 399 magnetization than other samples. Another reason for the 400 increase in the MI ratio can be attributed to the decrease of the 401 surface roughness. To see the effect of coating on the 402 roughness of the ribbon we used FESEM images of the surface. 403 Images of the free side of the bare ribbon and Gr/Ni-coated 404 ribbon are presented in Figure 7a,b, respectively. As observed, 405 f7 the roughness has decreased due to a surface coverage of 406 unevenness at the surface by the Gr/Ni composite layer. This 407 fact is in agreement with the increase of the MI ratio because 408 such a coating decreased the undesired emanating field at the 409 surface. The following electromagnetic model is presented to 410 understand the observed results.

4. MODEL FOR IMPEDANCE OF RIBBON/[GR/NI] **STRUCTURES**

In this section we describe a model for the MI response of the 413 ribbon/[Gr/Ni] structures. MI response can be found by 414 solving the Maxwell equations for the electromagnetic fields 415 and the Landau-Lifshitz-Gilbert (LLG) equation for the 416 magnetization dynamics by considering the boundary con- 417 ditions at the interfaces of the system. The changes caused by 418 the Gr/Ni layer on the MI response are related to stray fields 419 which magnetic Ni NPs induce. The magnetization distribu- 420 tion can be tuned by the stray fields and affect the permeability 421 and therefore the MI effect. One assumption is that the Gr/Ni 422 layer generates a spatially uniform effective field H_s on the 423 ribbon surface.²² Therefore, we are able to describe 424 qualitatively the influence of stray fields on the MI response. 425 The value of H_s is assumed to be proportional to the 426 concentration of MNPs in the Gr/Ni sample, because the Gr/ 427 Ni saturation magnetization increases linearly (see Figure 5a) 428 with the concentration of NPs. Also, we assume that the values 429 of the permeability in the magnetic layer are determined by the 430 magnetization rotation only because the DW motion is 431 strongly damped at sufficiently high frequencies (above 100 432 kHz).

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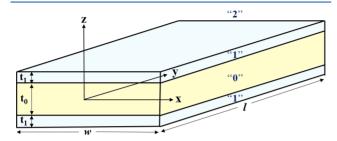


Figure 8. Schematic of the ribbon/[Gr/Ni] structures and the coordinate system.

436 There are three regions 0, 1, and 2 denoting the magnetic 437 ribbon layer, the Gr/Ni layer, and air. The film structure has 438 length l and width w < l and consists of thickness t_0 and t_1 for 439 the ribbon and Gr/Ni layer, respectively. The structure is 440 subjected to an alternating driving field $E = E_0 e^{-iwt}$, and an 441 external magnetic field H_e is parallel to the long side of the 442 sample (y-axis). It is assumed that the film length and width 443 are much larger than its thickness. Introducing the scalar and 444 vector potentials, φ and A, Maxwell's equations can be 445 expressed as $(\nabla \cdot A = 0 \text{ is used})$

$$\nabla^{2} \mathbf{A}_{j}(r, t) = \mu_{j} \sigma_{j} \left[\nabla \varphi_{j}(r, t) + \frac{\mathrm{d}}{\mathrm{d}t} \mathbf{A}_{j}(r, t) \right]$$

$$\nabla^{2} \varphi_{j}(r, t) = 0 \tag{4}$$

447 where j = 0, 1 corresponds to regions 0 and 1, and σ_i and μ_i 448 correspond to conductivity and permeability of the magnetic 449 ribbon for j = 0 and Gr/Ni layer for j = 1. The general 450 solutions for the vector potential in the three regions can be 451 expressed as

$$A_0 = \frac{iE_0}{\omega} [B_0 \cosh(\alpha_0 z) + C_0 \sinh(\alpha_0 z) - 1]$$
(5)

$$A_{1} = \frac{iE_{0}}{\omega} [B_{1} \cosh(\alpha_{1}z) + C_{1} \sinh(\alpha_{1}z) - 1]$$
(6)

$$A_2 = \frac{iE_0}{\omega} B_2 \left[\frac{l}{w} \ln \left(\frac{r+w}{r-w} \right) - \frac{2z}{w} \arctan \left(\frac{w}{2y} \frac{l}{r} \right) + \ln \left(\frac{l+r}{\sqrt{w^2 + 4z^2}} \right) \right]$$
(7)

where, $r = (w^2 + 4z^2 + l^2)^{1/2}$, $\alpha_k = (1 + i) \left(\frac{\omega \mu_i \sigma_i}{2}\right)^{1/2}$ 456 due to symmetry along the Z axis, $A_0(Z) = A_0(-Z)$, the 457 constant of C_0 is zero. The boundary conditions allow one to 458 find the constants B_0 , B_1 , C_1 , and B_2 in eqs 5–7 and describe 459 completely the distribution of the vector potential (see the 460 Appendix). When the potential distribution is obtained, 461 because the magnitude of the driving electric field is constant, 462 the impedance can be obtained as the proportionality factor 463 between the voltage and the total current in the device where

$$Z = \frac{lE_0}{2w} \left(\int_0^{t_0/2} J_0(z) \, dz + \int_{t_0/2}^{t_0/2+t_1} J_1(z) \, dz \right)^{-1}$$
(8)

465 where

$$J_0 = E_0 \sigma_0 B_0 \cosh(\alpha_0 z) \tag{9}$$

$$J_1 = E_0 \sigma_1 [B_1 \cosh(\alpha_1 z) + C_1 \sinh(\alpha_1 z)]$$

$$(10)_{467}$$

Finally, we obtain the impedance Z of the film with the Gr/ 468

$$\begin{split} Z &= \frac{1}{2w} \frac{1}{\gamma'} \Biggl[\cosh \Biggl(\frac{\alpha_1 t_0}{2} \Biggr) \cosh (\alpha_1 t) \Biggl[\Biggl(\tanh (\alpha_1 t) - \tanh \Biggl(\frac{\alpha_1 t_0}{2} \Biggr) \Biggr) \\ & \Biggl(\gamma + \beta \gamma' \tanh \Biggl(\frac{\alpha_0 t_0}{2} \Biggr) \Biggr) + \Biggl(1 - \tanh \Biggl(\frac{\alpha_1 t_0}{2} \Biggr) \tanh (\alpha_1 t) \Biggr) \\ & \Biggl(\gamma' + \beta \gamma \tanh \Biggl(\frac{\alpha_0 t_0}{2} \Biggr) \Biggr) \Biggr] \Biggr] \\ & / \Biggl[\frac{2\sigma_0}{\alpha_0} \tanh \Biggl(\alpha_0 \frac{t_0}{2} \Biggr) + \frac{2\sigma_1}{\alpha_1} \Biggl[\sinh (\alpha_1 t_1) + \beta \tanh \Biggl(\frac{\alpha_0 t_0}{2} \Biggr) \cosh (\alpha_1 t_1) \\ & - \beta \tanh \Biggl(\frac{\alpha_0 t_0}{2} \Biggr) \Biggr] \Biggr] \end{split}$$

Here,
$$t = \frac{t_0}{2} + t_1$$
, $\gamma = 1 + \ln \frac{2l}{w}$, $\gamma' = \frac{\pi}{w} \frac{\mu_1}{\mu_2 \alpha_1}$, and $\beta = \left(\frac{\mu_1 \sigma_0}{\mu_0 \sigma_1}\right)^{1/2}$.

4.1. Effect of the Gr/Ni Layer on Ribbon Permeability. 472 The MI response of the ribbon is controlled by the transverse 473 magnetic permeability. Transverse magnetic permeability 474 depends on factors like anisotropy distribution, domain 475 structure, mode of the magnetization variation, and so on. 476 Since in the experiment the current frequencies are sufficiently 477 high, the value of the transverse permeability in the FM layers 478 occurs because of the magnetization rotation of the ribbon. 479 Validation of this approximation is at sufficiently high 480 frequencies (>100 kHz) when the DW motion is damped. 20 481 Also, the anisotropy is considered to be in the plane of the 482

By minimizing the free energy one can find the magnet- 484 ization distribution in the FM layers. Taking into account the 485 effective stray field, H,, the minimization procedure results in 486 the following equation for the equilibrium magnetization angle, 487

$$H_a \sin(\theta - \psi) \cos(\theta - \psi) - H_s \sin(\theta - \varphi) - H_e \cos \theta = 0$$
(12) 489

Here, H_a is the anisotropy field in the FM layers, and ψ is the 490 deviation angle of the anisotropy axis from the transverse 491 direction.

In the magnetic susceptibility model, magnetization 493 dynamics is governed by the LLG equation and is given by

$$\frac{\partial \mathbf{m}}{\partial t} = -\gamma \mathbf{m} \times \mathbf{H}_{\text{eff}} + \alpha \mathbf{m} \times \frac{\partial \mathbf{m}}{\partial t}$$
(13) ₄₉₅

where m is vector magnetization, $H_{\rm eff}$ is the effective field, γ is 496 the electron gyromagnetic ratio, and lpha is the Gilbert damping 497 constant. The solution of the linearized LLG equation results 498 in the following expression for the transverse permeability in 499 the ribbon layer:50

$$\mu_0 = 1 + \frac{\omega_m [\omega_m + \omega_1 - i\alpha\omega] \sin^2 \theta}{[\omega_m + \omega_1 - i\alpha\omega][\omega_2 - i\alpha\omega] - \omega^2}$$
(14) ₅₀₁

Here, $\omega_m = 4\pi\gamma M_s$, M_s is the saturation magnetization of the 502 ribbon, $\omega = 2\pi f$ is the angular frequency, and

$$\omega_1 = \gamma [H_a \cos^2(\theta - \psi) - H_s \cos(\theta - \varphi) + H_e \sin \theta]$$
(15) 504

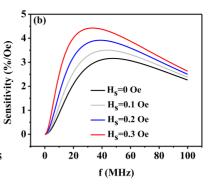


Figure 9. (a) Field dependence of the MI ratio $\Delta Z/Z$ calculated at $f=\frac{\omega}{2\pi}=10$ MHz for the ribbon without the Gr/Ni layer and the ribbon with the Gr/Ni layer for different values of the effective stray field H_s . (b) Frequency dependence of the impedance sensitivity calculated by means of eq 17 for different values of H_s . Parameters used for calculations are w=8 mm, l=4 cm, $t_0=20$ μm, $t_1=10$ μm, $\sigma_0=5.81\times10^7$ $\frac{1}{\Omega_{\rm m}}$, $\sigma_1=10^3$ $\frac{1}{\Omega_{\rm m}}$, $M_s=800$ Oe, $\theta=0.75\pi$, $\varphi=-0.1\pi$, $\psi=0.48\pi$, $\alpha=0.1$, $H_a=4$ Oe.

$$\omega_2 = \gamma [H_a \cos 2(\theta - \psi) - H_s \cos(\theta - \varphi) + H_e \sin \theta]$$
(16)

Thus, the MI response in the ribbon with a Gr/Ni layer can 507 be calculated as follows. The first step is the determination of 508 the transverse permeability in the FM layer by using eq 14. 509 The second step is substitution of eq 14 into eq 11 and then 510 the calculation of the impedance Z of the film with the Gr/Ni 1 layer. When the impedance Z is determined, the MI response 512 of the ribbon with the Gr/Ni layer can be obtained by means 513 of eq 2.

4.2. MI Response of Ribbon/[Gr/Ni] Structures: A S15 Comparison between the Experiment and Modeling. S16 Figure 9a shows the field dependence of the MI ratio S17 calculated at 10 MHz for the ribbon without the Gr/Ni layer S18 and the ribbon with the Gr/Ni layer considering different S19 values for the effective stray field, H_s . Here, only results for the S20 range of positive fields are presented because the MI ratio is S21 symmetric with respect to the sign of the external field. When S22 the concentration of the MNPs increases the saturation S23 magnetization increases too, and in result the effective stray S24 field increases. As a result, the MI ratio shifts toward low S25 external fields with increasing H_s and exhibits a dependence S26 similar to the one observed in the experiment.

For analyzing the variation of the MI effect, let us introduce the impedance field sensitivity, which is defined as follows:

$$S = \frac{|\Delta Z|}{|\Delta H_e|} = \frac{Z(H_e = -H_a) - Z(H_e = 0)}{H_a}$$
(17)

For different values of the effective stray field, H_s , Figure 9b 530 531 represents the frequency dependence of the impedance 532 sensitivity calculated by means of eq 17. At relatively low frequencies the field sensitivity increases and attains a peak at f = 20 MHz. The position of the highest sensitivity shifts to lower frequencies with a growth of the effective stray field, H_s. The proposed model allows one to describe qualitatively the main features of the experimental results of the MI response of ribbon coated with a Gr/Ni layer. However, some 538 a 539 experimental results cannot be explained according to the 540 model. It is demonstrated that the contribution of the stray 541 fields induced by MNPs in the Gr/Ni layer leads to a shift 542 toward low external fields with an increase of H_s . It should be 543 noted that the model does not describe the essential increase 544 of the MI response with an increase in the concentration of 545 MNPs in the Gr/Ni layer. The disagreement between

theoretical and experimental results may be attributed to the $_{546}$ fact that, in the proposed model, the contribution of surface $_{547}$ roughness was not considered. There are many experimental $_{548}$ works that demonstrated the fact that reduction of roughness $_{549}$ can lead to increase of the MI response. 27,28,31,33 Closure of $_{550}$ magnetic flux paths due to surface modification of the ribbons $_{551}$ is explained for the increase of the MI response. Also, in our $_{552}$ model, it is shown that for the stray fields produced by the $_{553}$ MNPs, H_s describes the effect of the Gr/Ni layer on the MI of $_{554}$ the ribbon qualitatively. Here, for an exact calculation the $_{555}$ amount of H_s should be gained with exact distributions $_{556}$ through numerical solution.

5. CONCLUSION

In summary, the present study demonstrates that electro-558 chemically exfoliated Gr is a promising method for fabricating 559 magnetic Gr sheets/Ni nanocrystal composites in high quality. 560 By changing the molarity of a NiCl₂ aqueous solution, different 561 magnetic strengths of the final composite material were 562 achieved. Different molarities of 0.05, 0.075, and 0.1 M of 563 NiCl₂ for fabrication of the samples result in different 564 magnetization of the material. The higher molarity results in 565 lower magnetization. In addition to the focus on the novel 566 fabrication of materials, we further investigate the application 567 of the synthesized materials in MI sensors with an observed 568 enhanced ratio and sensitivity when applied atop an MI sensor. 569 The experimental observation of the MI response of our sensor 570. shows higher MI% for the sensor coated with the Gr/Ni 571 sample with a higher magnetization. By solving the linearized 572. Maxwell equation and LLG equation for the magnetization 573 dynamics we could find the origin of the observed MI 574 behaviors under the presence of Gr/Ni composite. The results 575 can be considered for future developments of MI-based 576 sensors and biosensors.

APPENDIX

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Boundary conditions require that A and $\frac{1}{\mu} \frac{dA}{dz}$ be continuous: 579

1)

505

578

$$A_0 = A_1 \qquad z = \frac{t_0}{2}$$

$$\mu_1 \frac{\mathrm{d}}{\mathrm{d}z} A_0 = \mu_0 \frac{\mathrm{d}}{\mathrm{d}z} A_1$$

$$A_1 = A_2 \qquad z = \frac{t_0}{2} + t_1$$

$$\mu_2 \frac{\mathrm{d}}{\mathrm{d}z} \mathbf{A_1} = \mu_1 \frac{\mathrm{d}}{\mathrm{d}z} \mathbf{A_2} \tag{A1}$$

By substitution of eqs 5-7 into eq A1 with the 581 582 approximation of A_2 for $w \ll l$:

$$B_0 \cosh(x_0) - B_1 \cosh(y_0) - C_1 \sinh(y_0) = 0$$

$$B_0 \beta \sinh(x_0) - B_1 \sinh(y_0) - C_1 \cosh(y_0) = 0$$

$$B_1 \cosh(z_0) + C_1 \sinh(z_0) - B_2 \gamma = 1$$

$$B_1 \sinh(z_0) + C_1 \cosh(z_0) + B_2 \gamma' = 0$$
(A2)

584 where

583

$$x_0 = \frac{\alpha_0 t_0}{2}$$
 $y_0 = \frac{\alpha_1 t_0}{2}$ $z_0 = \alpha_1 t$ $t = \frac{t_0}{2} + t_1$ $\gamma = 1 + \ln \frac{2l}{w}$ $\gamma' = \frac{\pi}{w} \frac{\mu_1}{\mu_2 \alpha_1}$

Solving for the coefficients, we obtain

$$\begin{split} B_0 &= \frac{1}{E} \\ B_1 &= \frac{1}{E} (\cosh(x_0) \cosh(y_0) - \beta \sinh(x_0) \sinh(y_0)) \\ C_1 &= \frac{1}{E} (\beta \sinh(x_0) \cosh(y_0) - \sinh(y_0) \cosh(x_0)) \\ E &= \frac{1}{\gamma'} \cosh(x_0) \cosh(y_0) \cosh(z_0) [(\tanh(z_0) - \tanh(y_0)) \\ (\gamma + \beta \gamma' \tanh(x_0)) + (1 - \tanh(y_0) \tanh(z_0)) \\ (\gamma' + \beta \gamma \tanh(x_0))] \end{split}$$

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595 The manuscript was written through contributions of all 596 authors. All authors have given approval to the final version of

597 the manuscript.

598 Notes

599 The authors declare no competing financial interest.

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